

User-Independent Detection of Swipe Pressure using a Thermal Camera for Natural Surface Interaction

Timothy Dunn, Sean Banerjee, Natasha Kholgade Banerjee
Clarkson University, Potsdam NY

User Interaction in Augmented Reality



- **Handheld controllers and touchscreens are currently state of the art**
- **Direct user interaction with natural surfaces reduces the need for commercial equipment**



<http://fortune.com/2015/06/11/oculus-microsoft-partnership/>



<https://mashable.com/2017/08/04/sony-touch-handson/#DdfTiLvSuiqd>

Natural User Interfaces vs Touchscreens

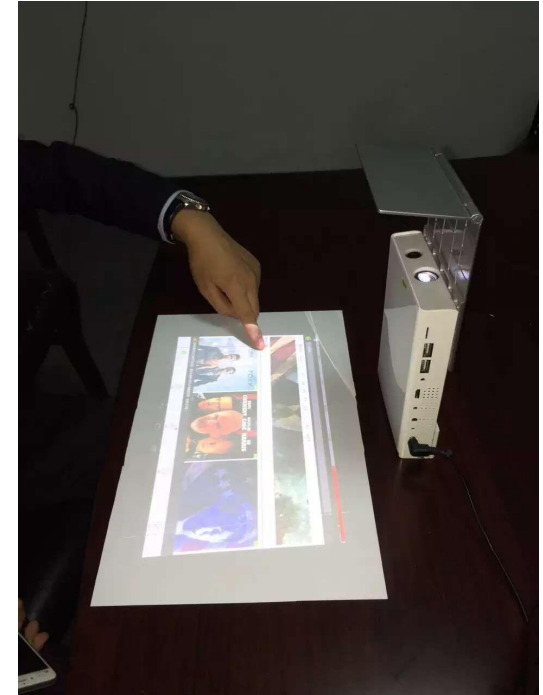


Limitations of surface instrumentation:

- expensive
- may ruin aesthetic appearance
- often impractical
- fixed location

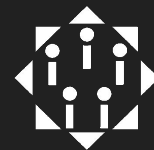


<https://www.speechi.net/en/home/interactive-screens/speechitouch-84-giant-touch-screen-hd-and-uhd-interactive-screen/>



https://www.alibaba.com/product-detail/Newest-Laser-to-uch-pico-projector-build_60390719367.html

Our Work: Detecting Swipe Pressure



- Pressure is an intuitive gesture for many applications
- Differentiate between hard and soft swipes
- Test multiple materials
- No per-user configuration required

SOFT



HARD

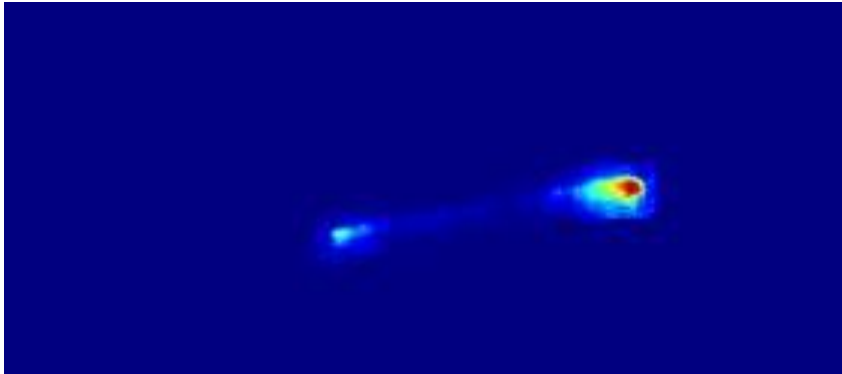


RGB vs Thermal Cameras

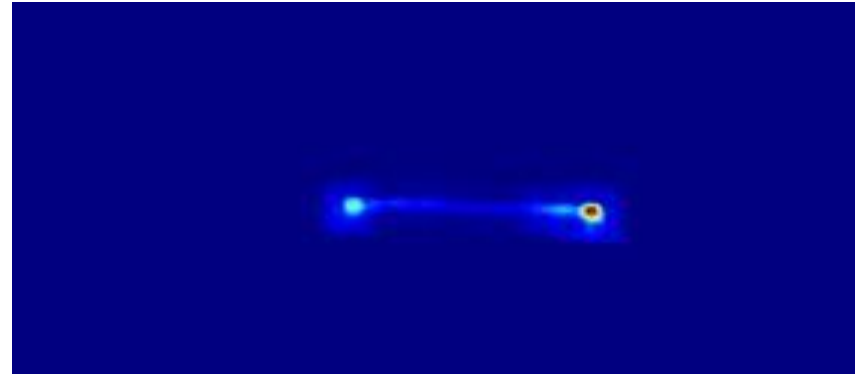


Greater pressure corresponds to increased frictional heat

SOFT



HARD

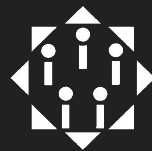


Related Work



- **Oka et. al.:** real-time tracking of multiple fingertips
- **Larson et. al., *HeatWave*:** gesture recognition
- **Iwai and Sato, *ThermoTablet*:** temperature-based interactions
- **Kurz, *ThermalTouch*:** identify and locate touched objects
- **Saba et. al., *DanteVision*:** train a per-user classifier

Related Work



- **Oka et. al.:** real-time tracking of multiple fingertips
- **Larson et. al., *HeatWave*:** gesture recognition
- **Iwai and Sato, *ThermoTablet*:** temperature-based interactions
- **Kurz, *ThermalTouch*:** identify and locate touched objects
- **Saba et. al., *DanteVision*:** train a per-user classifier

A user-independent "out of the box" classifier for swipe pressure

Experimental Setup



- **FLIR Vue Pro Thermal Camera**
 - 640x512 resolution
 - captures 30 fps
- **Plywood and Paper**
 - anchored to desktop surface



Data Collection

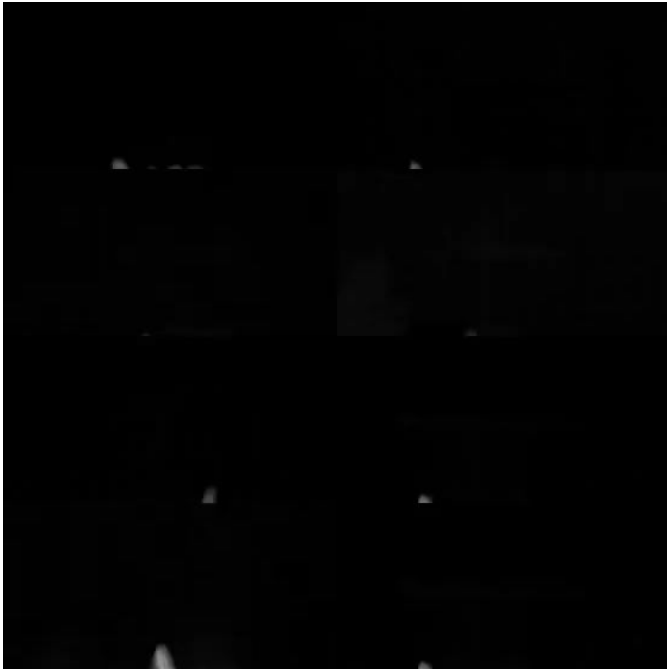


- **Nine test subjects**
 - age range of 18 to 37 years
- **Collected 16 hard and 16 soft swipes for each material**
 - 5 second delay between soft swipes
 - 10 second delay between hard swipes
- **Allowed swipes of any length or direction**

Examples



HARD



SOFT



Swipe Extraction



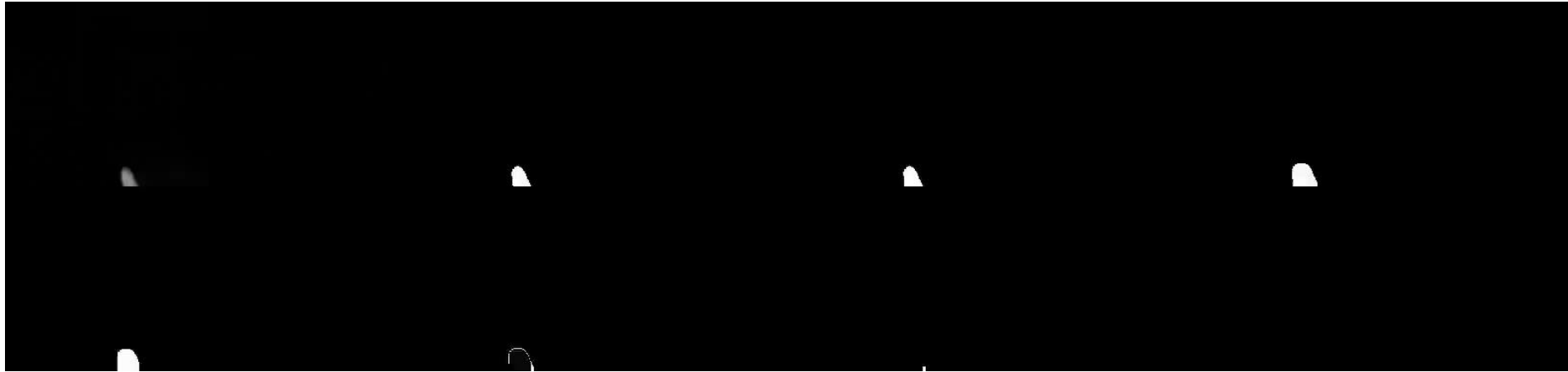
- Perform static background subtraction
- Cropped video to desired region
- Thresholded at fixed value
- Performed morphological filtering to remove hand from video



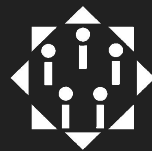
Swipe Extraction



- Perform static background subtraction
- Cropped video to desired region
- Thresholded at fixed value
- Performed morphological filtering to remove hand from video



Swipe Extraction



- Perform static background subtraction
- Cropped video to desired region
- Thresholded at fixed value
- Performed morphological filtering to remove hand from video



Curve Fitting



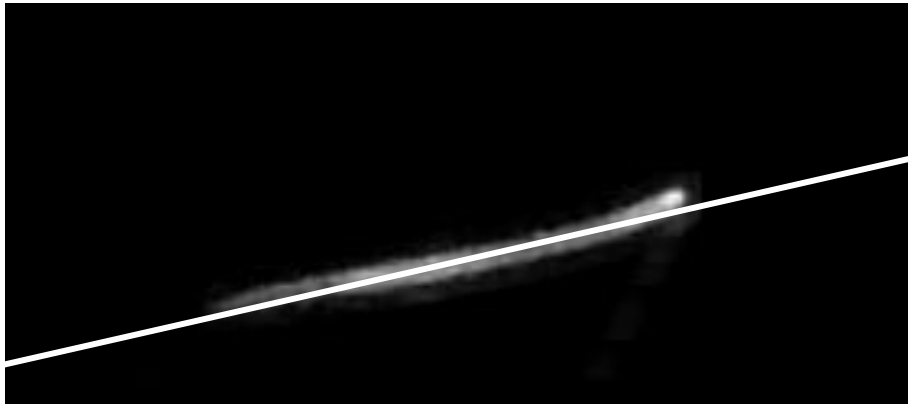
- Accumulate intensities over time into single image
- Represent swipe by translated and rotated quadratic function
- Within 10 pixels of this function is defined as region of interest



Curve Fitting



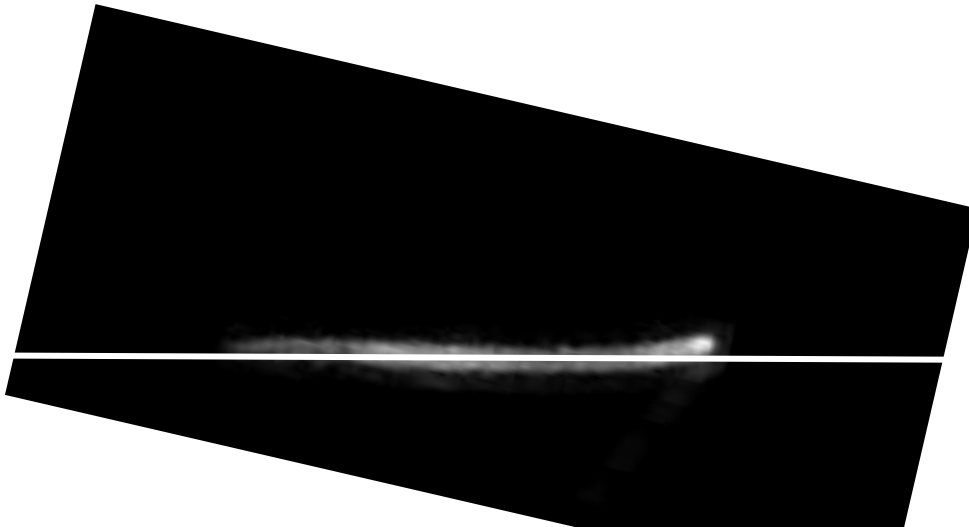
- Accumulate intensities over time into single image
- Represent swipe by translated and rotated quadratic function
- Within 10 pixels of this function is defined as region of interest



Curve Fitting



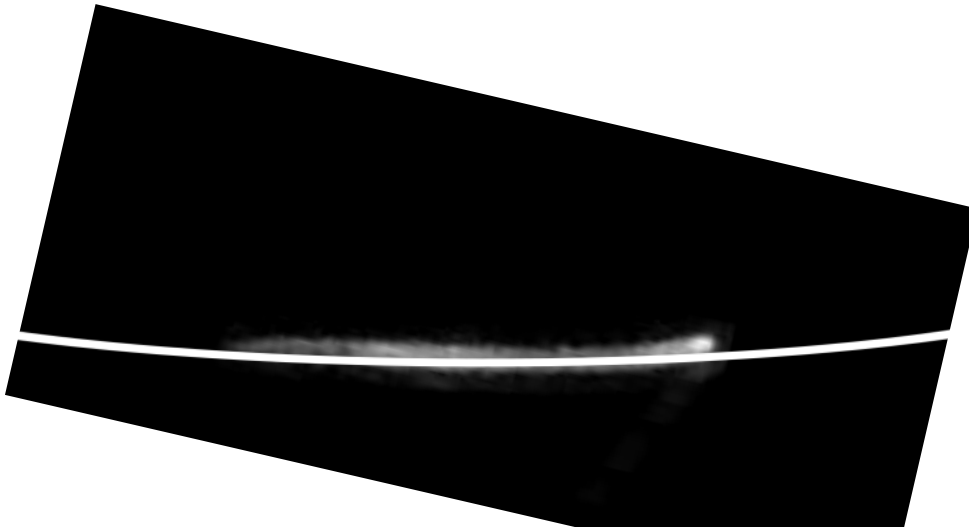
- Accumulate intensities over time into single image
- Represent swipe by translated and rotated quadratic function
- Within 10 pixels of this function is defined as region of interest



Curve Fitting



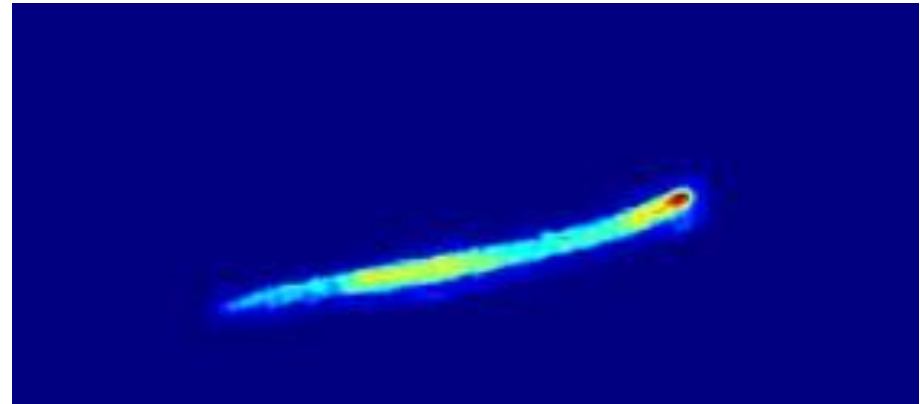
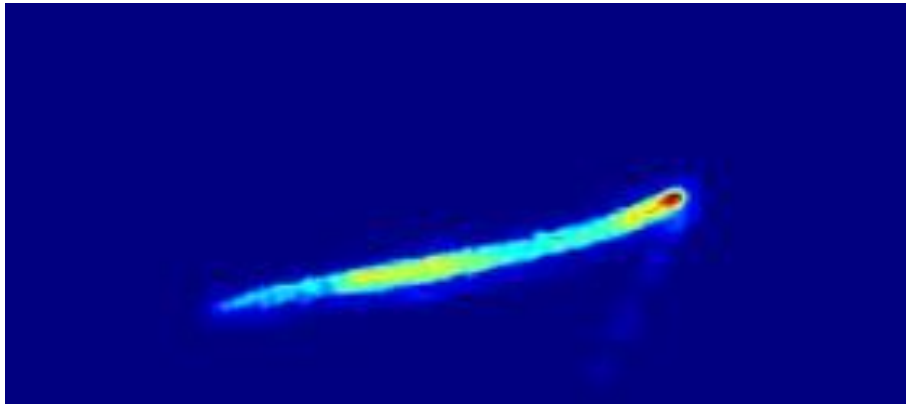
- Accumulate intensities over time into single image
- Represent swipe by translated and rotated quadratic function
- Within 10 pixels of this function is defined as region of interest



Curve Fitting



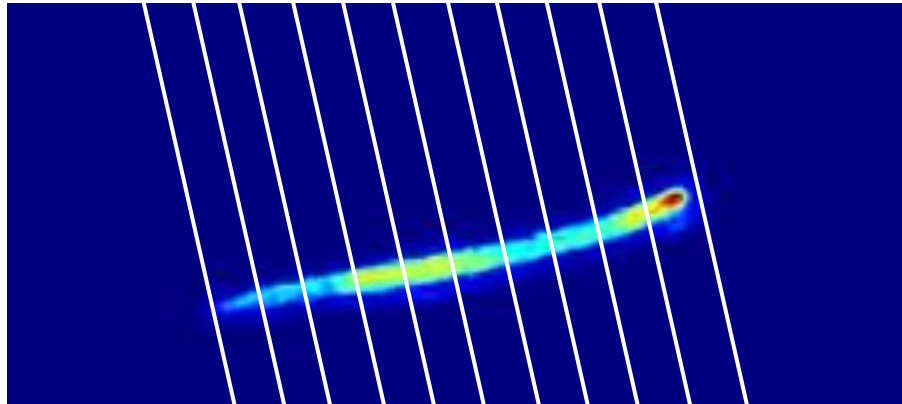
- Accumulate intensities over time into single image
- Represent swipe by translated and rotated quadratic function
- Within 10 pixels of this function is defined as region of interest



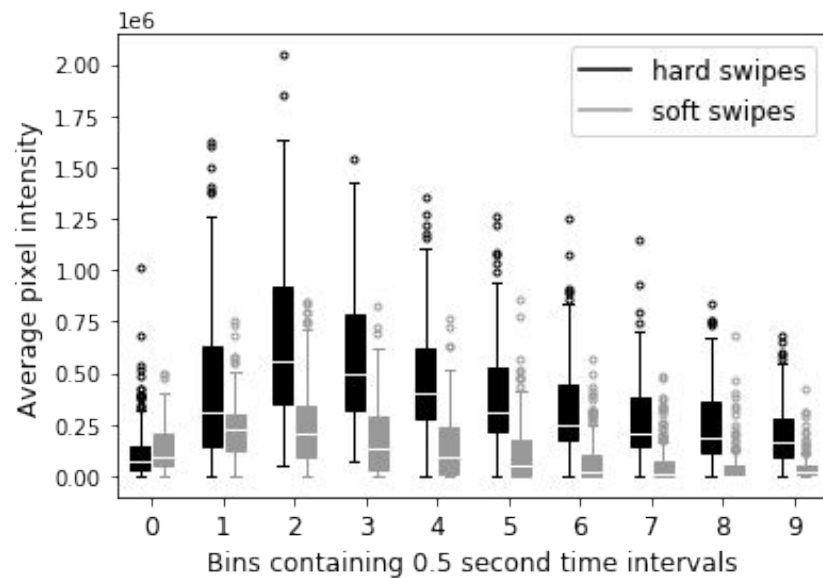
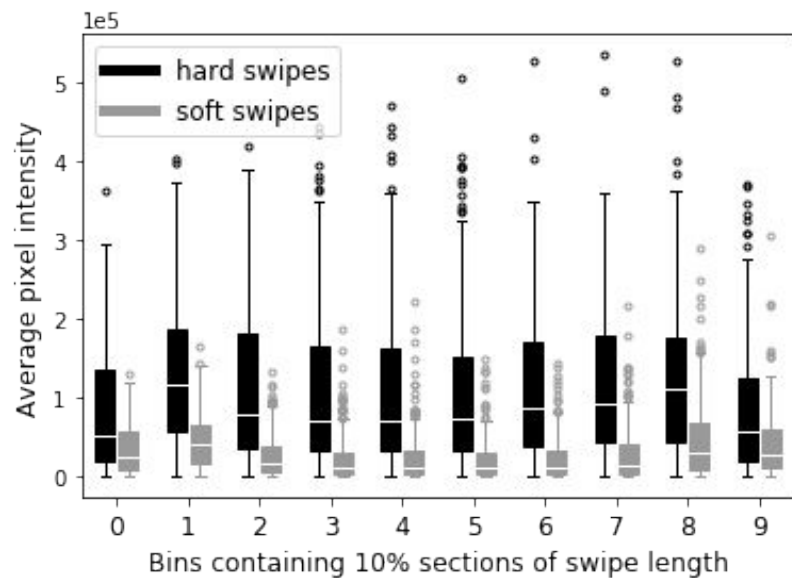
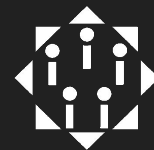
Classification



- **Random Forest Classifier**
 - 500 trees
- **30 features used total**
 - 10 bins along swipe length, used avg and max pixel intensities within bin
 - 10 bins over time, used total pixel intensities



Results



Results



		Predicted Class	
		Hard	Soft
Actual Class	Hard	0.82	0.18
	Soft	0.30	0.70

All Materials

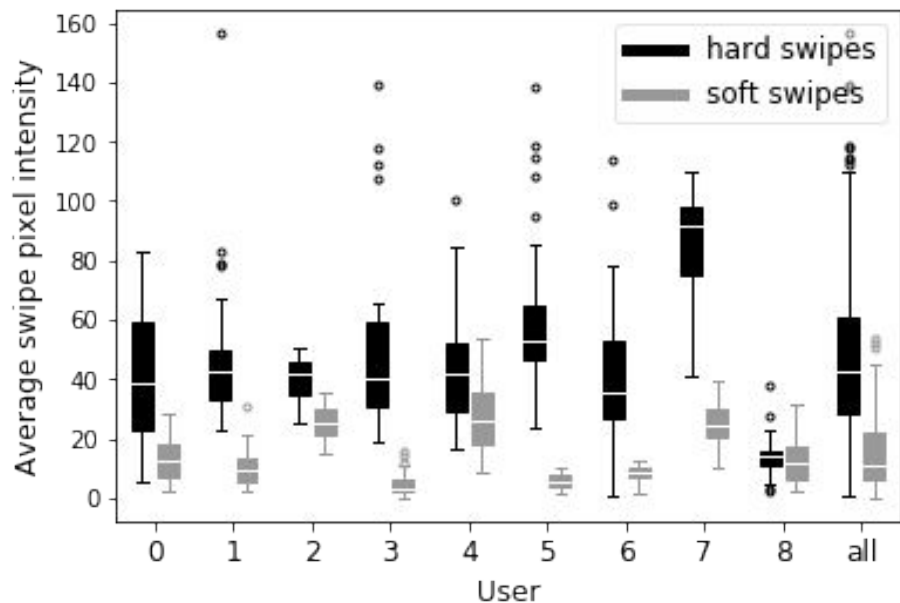
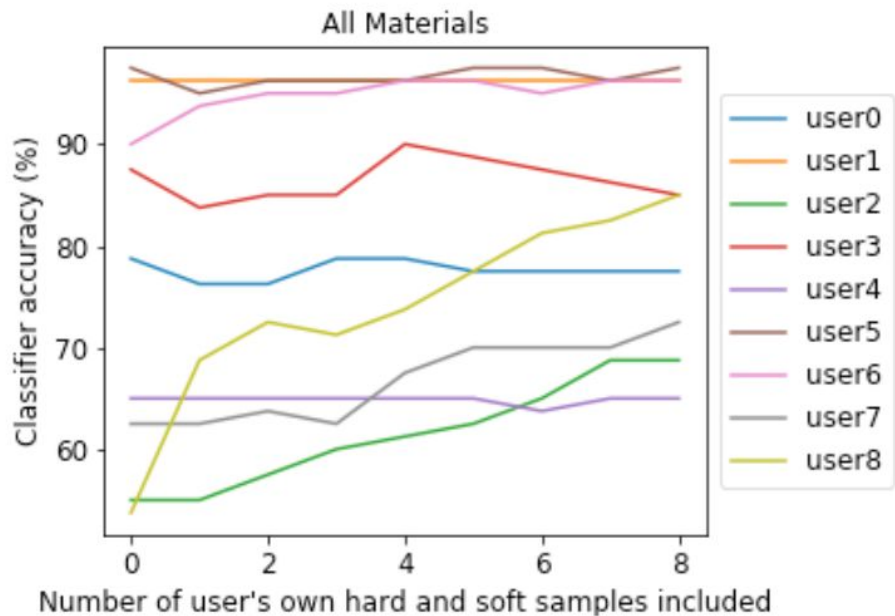
		Predicted Class	
		Hard	Soft
Actual Class	Hard	0.71	0.29
	Soft	0.18	0.82

Paper Only

		Predicted Class	
		Hard	Soft
Actual Class	Hard	0.93	0.07
	Soft	0.16	0.84

Wood Only

Adjusting the Classifier to a User



Conclusions and Future Work



- **Thermal cameras can be used to effectively identify user gestures**
 - **Calibration for each user is not required**
 - **Classification rate can be improved over time**
-
- **Test additional common materials**
 - **Identify more complex swiping patterns**
 - **Deal with heat dissipation**